

Tasks and Functions of the Analog Interface
SSP and SYSKON Product Ranges in Comparison

15th May 2011

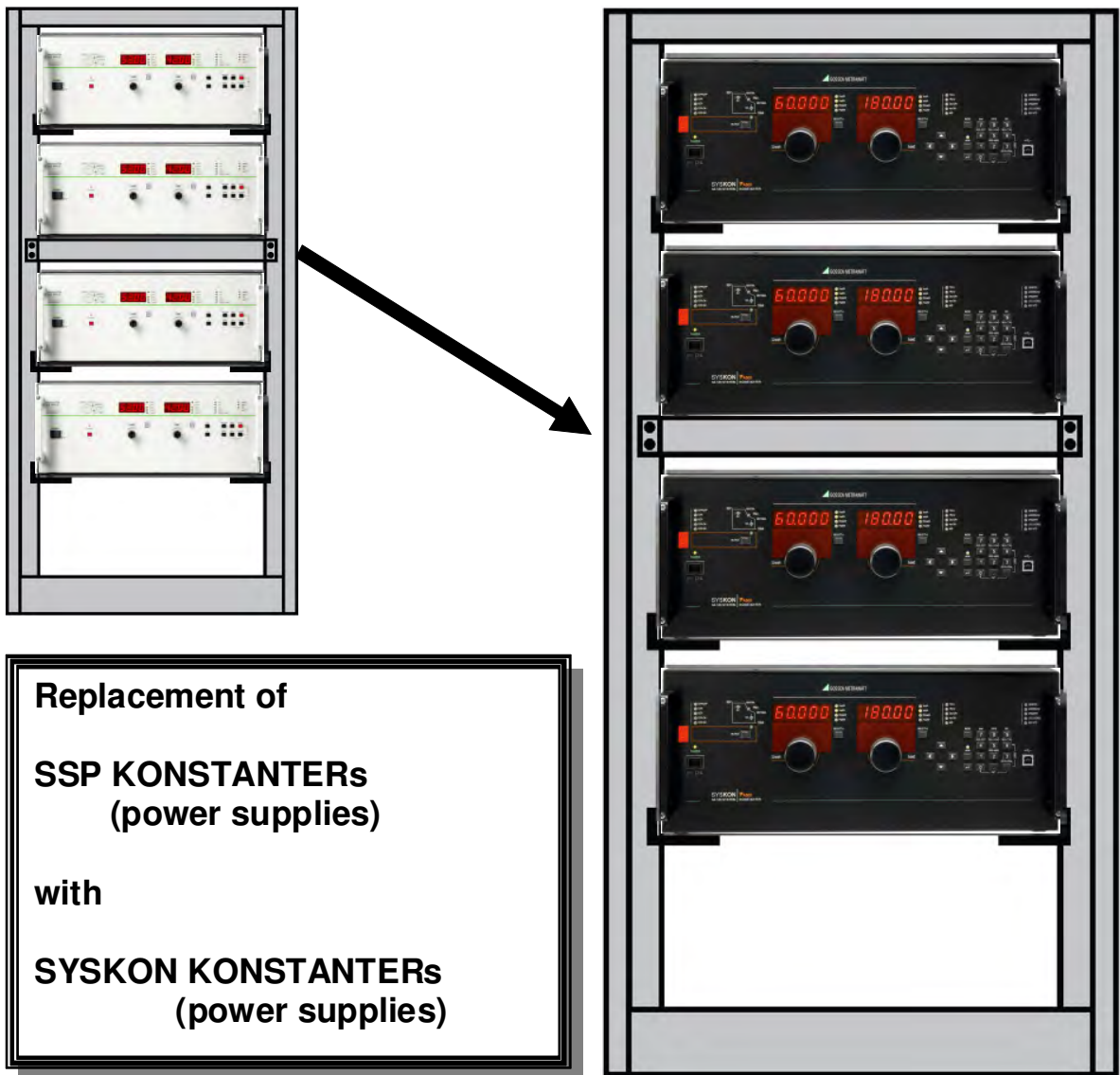
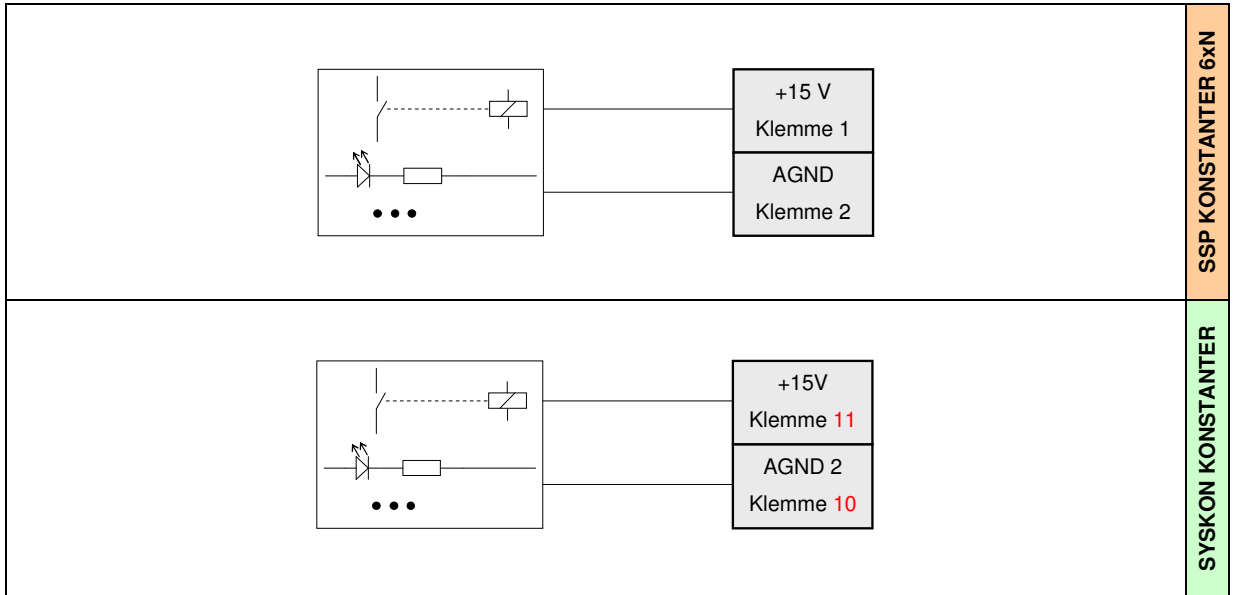


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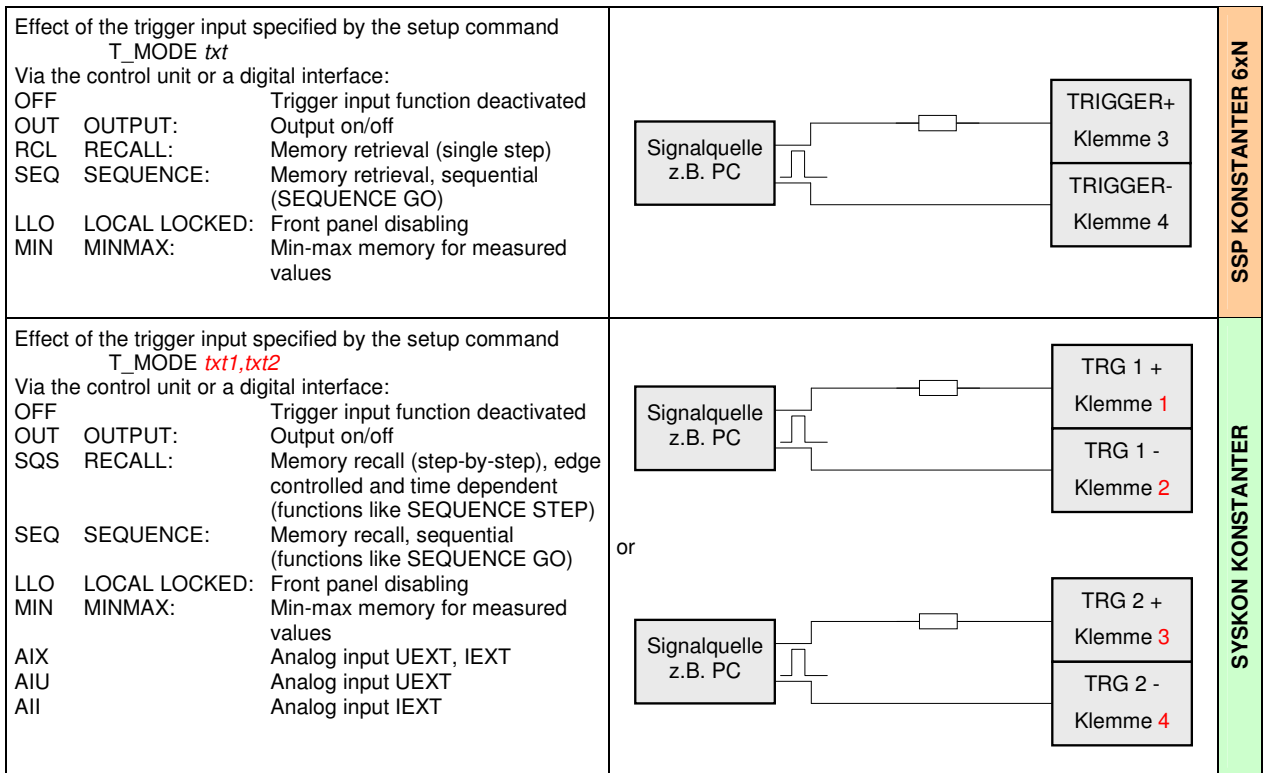
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1. Adaptation of Wiring and Control of the Analog Interface when Replacing the SSP KONSTANTER with the SYSKON KONSTANTER

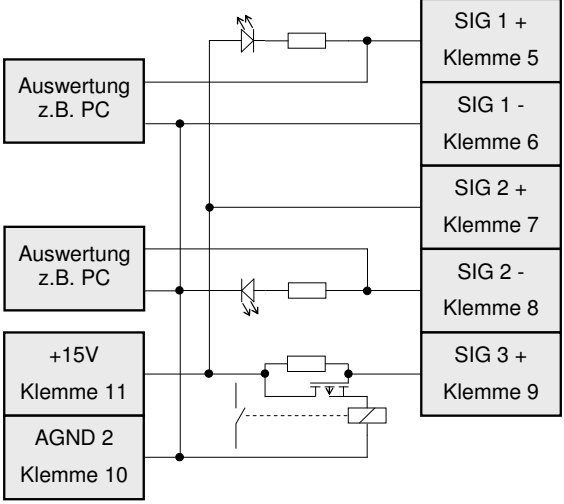
1.1. Auxiliary Power



1.2. Trigger Input



1.3. Signal output

None		SSP KONSTANTER 6xN												
<p>Examples of signal output usage:</p> <p>SIG 1: With pull-up resistor</p> <table border="1" data-bbox="363 645 767 696"> <tr> <td>Signal Evaluation</td> <td>Active Low</td> <td>Inactive High</td> </tr> </table> <p>SIG 2: With pull-down resistor</p> <table border="1" data-bbox="363 768 767 819"> <tr> <td>Signal Evaluation</td> <td>Active High</td> <td>Inactive Low</td> </tr> </table> <p>SIG 3: Control of a semiconductor switch for switching a relay</p> <table border="1" data-bbox="363 913 767 965"> <tr> <td>Signal</td> <td>Active</td> <td>Inactive</td> </tr> <tr> <td>Relay coil</td> <td>Active</td> <td>Inactive</td> </tr> </table> <p>Internal power supply (+15 V – AGND 1/2) can also be replaced with an external source. However, if SIG 3 is used reference to AGND 1/2 must be established.</p>	Signal Evaluation	Active Low	Inactive High	Signal Evaluation	Active High	Inactive Low	Signal	Active	Inactive	Relay coil	Active	Inactive		SYSKON KONSTANTER
Signal Evaluation	Active Low	Inactive High												
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Signal	Active	Inactive												
Relay coil	Active	Inactive												

1.4. Regulating Output Voltage

<p>Conversion table for analog voltage regulation: $U_{Usetanalog} = f_{Usetanalog} \times U_{set_PC}$</p> <table border="1"> <tr> <td>U_{anom}</td> <td>$f_{Usetanalog}$</td> </tr> <tr> <td>40 V</td> <td>$1/8 \text{ V/V}$</td> </tr> <tr> <td>52 V</td> <td>$5/52 \text{ V/V}$</td> </tr> <tr> <td>80 V</td> <td>$1/16 \text{ V/V}$</td> </tr> </table>	U_{anom}	$f_{Usetanalog}$	40 V	$1/8 \text{ V/V}$	52 V	$5/52 \text{ V/V}$	80 V	$1/16 \text{ V/V}$		<p>SSP KONSTANTER 6xN</p>				
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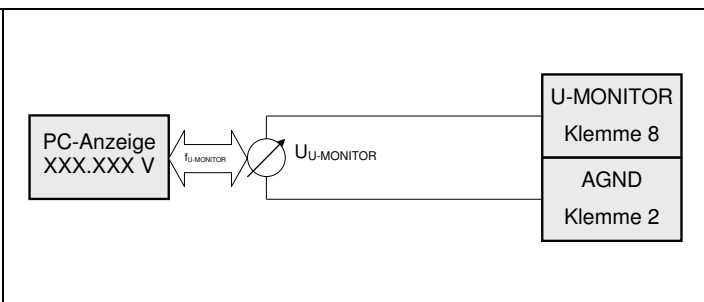
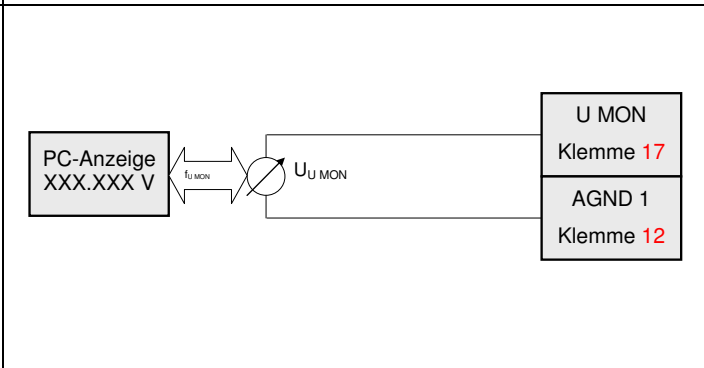
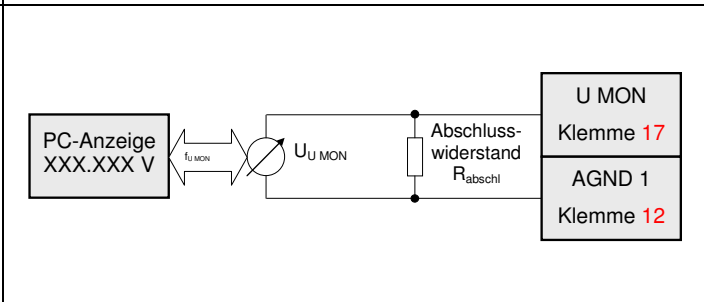
Original	Replacement	Voltage U_{U_EXT}	Required Action Correction Factor / Series Resistor
SSP 500-40(-25) SSP 1000-40(-50) SSP 2000-40(-100) SSP 3000-40(-150)	SYSKON XXXX-60-XXX	$U_{U_EXT}(SYSKON) = 2/3 \times U_{Uset}(SSP)$	5 kΩ series resistor
SSP 500-52(-25) SSP 1000-52(-50) SSP 2000-52(-100) SSP 3000-52(-150)	SYSKON XXXX-60-XXX	$U_{U_EXT}(SYSKON) = 13/15 \times U_{Uset}(SSP)$	1.54 kΩ series resistor
SSP 500-80(-12.5) SSP 1000-80(-25) SSP 2000-80(-50) SSP 3000-80(-75)	SYSKON XXXX-60-XXX	$U_{U_EXT}(SYSKON) = 4/3 \times U_{Uset}(SSP)$	Conversion with a factor of $4/3$

1.5. Regulating Output Current

<p>Conversion table for analog current regulation: $U_{\text{Isetanalog}} = f_{\text{Isetanalog}} \times I_{\text{set_PC}}$</p> <table border="1"> <thead> <tr> <th>I_{anom}</th> <th>$f_{\text{Isetanalog}}$</th> </tr> </thead> <tbody> <tr> <td>12.5 A</td> <td>$\frac{2}{5} \text{ V/A}$</td> </tr> <tr> <td>25 A</td> <td>$\frac{1}{5} \text{ V/A}$</td> </tr> <tr> <td>50 A</td> <td>$\frac{1}{10} \text{ V/A}$</td> </tr> <tr> <td>75 A</td> <td>$\frac{2}{30} \text{ V/A}$</td> </tr> <tr> <td>100 A</td> <td>$\frac{1}{20} \text{ V/A}$</td> </tr> <tr> <td>150 A</td> <td>$\frac{1}{30} \text{ V/A}$</td> </tr> </tbody> </table>	I_{anom}	$f_{\text{Isetanalog}}$	12.5 A	$\frac{2}{5} \text{ V/A}$	25 A	$\frac{1}{5} \text{ V/A}$	50 A	$\frac{1}{10} \text{ V/A}$	75 A	$\frac{2}{30} \text{ V/A}$	100 A	$\frac{1}{20} \text{ V/A}$	150 A	$\frac{1}{30} \text{ V/A}$		<p>SSP KONSTANTER 6xN</p>														
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Original	Replacement	Voltage $U_{I\text{EXT}}$	Required Action Correction Factor / Series Resistor
SSP 500-80(-12.5)	SYSKON 1500-60-60	$U_{I\text{EXT}}(\text{SYSKON}) = \frac{5}{24} \times U_{I\text{set}}(\text{SSP})$	38 kΩ series resistor
SSP 500-40(-25)	SYSKON 1500-60-60	$U_{I\text{EXT}}(\text{SYSKON}) = \frac{5}{12} \times U_{I\text{set}}(\text{SSP})$	14 kΩ series resistor
SSP 500-52(-25)			
SSP 1000-80(-25)			
SSP 1000-40(-50)	SYSKON 1500-60-60	$U_{I\text{EXT}}(\text{SYSKON}) = \frac{5}{6} \times U_{I\text{set}}(\text{SSP})$	2 kΩ series resistor
SSP 1000-52(-50)			
SSP 2000-80(-50)			
SSP 2000-80(-50)	SYSKON 3000-60-120	$U_{I\text{EXT}}(\text{SYSKON}) = \frac{5}{12} \times U_{I\text{set}}(\text{SSP})$	14 kΩ series resistor
SSP 3000-80(-75)	SYSKON 1500-60-60	$U_{I\text{EXT}}(\text{SYSKON}) = \frac{5}{4} \times U_{I\text{set}}(\text{SSP})$	Conversion with a factor of $\frac{5}{4}$
	SYSKON 3000-60-120	$U_{I\text{EXT}}(\text{SYSKON}) = \frac{5}{8} \times U_{I\text{set}}(\text{SSP})$	6 kΩ series resistor
SSP 2000-40(-100)	SYSKON 1500-60-60	$U_{I\text{EXT}}(\text{SYSKON}) = \frac{5}{3} \times U_{I\text{set}}(\text{SSP})$	Conversion with a factor of $\frac{5}{3}$
SSP 2000-52(-100)	SYSKON 3000-60-120	$U_{I\text{EXT}}(\text{SYSKON}) = \frac{5}{6} \times U_{I\text{set}}(\text{SSP})$	2 kΩ series resistor
SSP 3000-40(-150)	SYSKON 3000-60-120	$U_{I\text{EXT}}(\text{SYSKON}) = \frac{5}{4} \times U_{I\text{set}}(\text{SSP})$	Conversion with a factor of $\frac{5}{4}$
SSP 3000-52(-150)	SYSKON 4500-60-180	$U_{I\text{EXT}}(\text{SYSKON}) = \frac{5}{6} \times U_{I\text{set}}(\text{SSP})$	2 kΩ series resistor

1.6. Analog Measured Value for Output Voltage

<p>Conversion table for analog voltage monitoring $U_{\text{meas_PC}} = f_{U\text{-MONITOR}} \times U_{U\text{-MONITOR}}$</p> <table border="1"> <thead> <tr> <th>U_{anom}</th> <th>$f_{U\text{-MONITOR}}$</th> </tr> </thead> <tbody> <tr> <td>40 V</td> <td>$4 \frac{\text{V}}{\text{V}}$</td> </tr> <tr> <td>52 V</td> <td>$5.2 \frac{\text{V}}{\text{V}}$</td> </tr> <tr> <td>80 V</td> <td>$8 \frac{\text{V}}{\text{V}}$</td> </tr> </tbody> </table>	U_{anom}	$f_{U\text{-MONITOR}}$	40 V	$4 \frac{\text{V}}{\text{V}}$	52 V	$5.2 \frac{\text{V}}{\text{V}}$	80 V	$8 \frac{\text{V}}{\text{V}}$		SSP KONSTANTER 6xN				
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U_{anom}	SSP	SYSKON	$R_{\text{terminating}}$	$f_{U\text{ MON}}$										
80 V	60 V	60 V	24 kΩ	$8 \frac{\text{V}}{\text{V}}$										

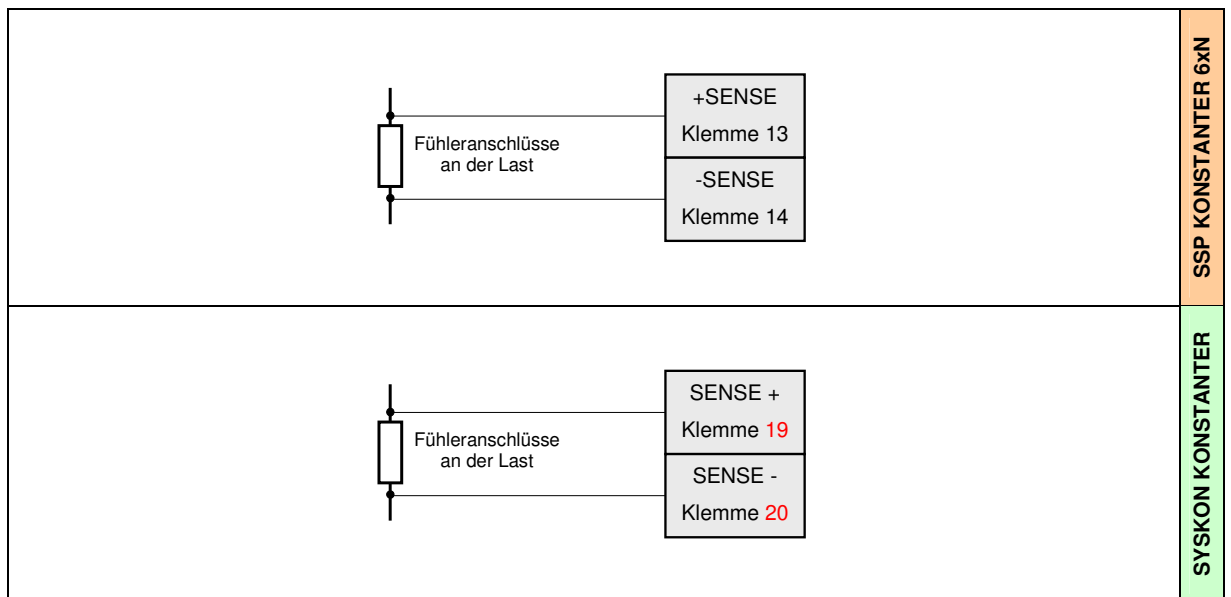
Original	Replacement	Voltage $U_{U\ MON}$	Required Action Correction Factor / Terminating
SSP 500-40(-25) SSP 1000-40(-50) SSP 2000-40(-100) SSP 3000-40(-150)	SYSKON XXXX-60-XXX	$U_{U\ MON}(SYSKON) = \frac{2}{3} \times U_{U-MONITOR}(SSP)$	Conversion with a factor of $\frac{3}{2}$
SSP 500-52(-25) SSP 1000-52(-50) SSP 2000-52(-100) SSP 3000-52(-150)	SYSKON XXXX-60-XXX	$U_{U\ MON}(SYSKON) = \frac{13}{15} \times U_{U-MONITOR}(SSP)$	Conversion with a factor of $\frac{15}{13}$
SSP 500-80(-12.5) SSP 1000-80(-25) SSP 2000-80(-50) SSP 3000-80(-75)	SYSKON XXXX-60-XXX	$U_{U\ MON}(SYSKON) = \frac{4}{3} \times U_{U-MONITOR}(SSP)$	24 k Ω terminating resistor

1.7. Analog Measured Value for Output Current

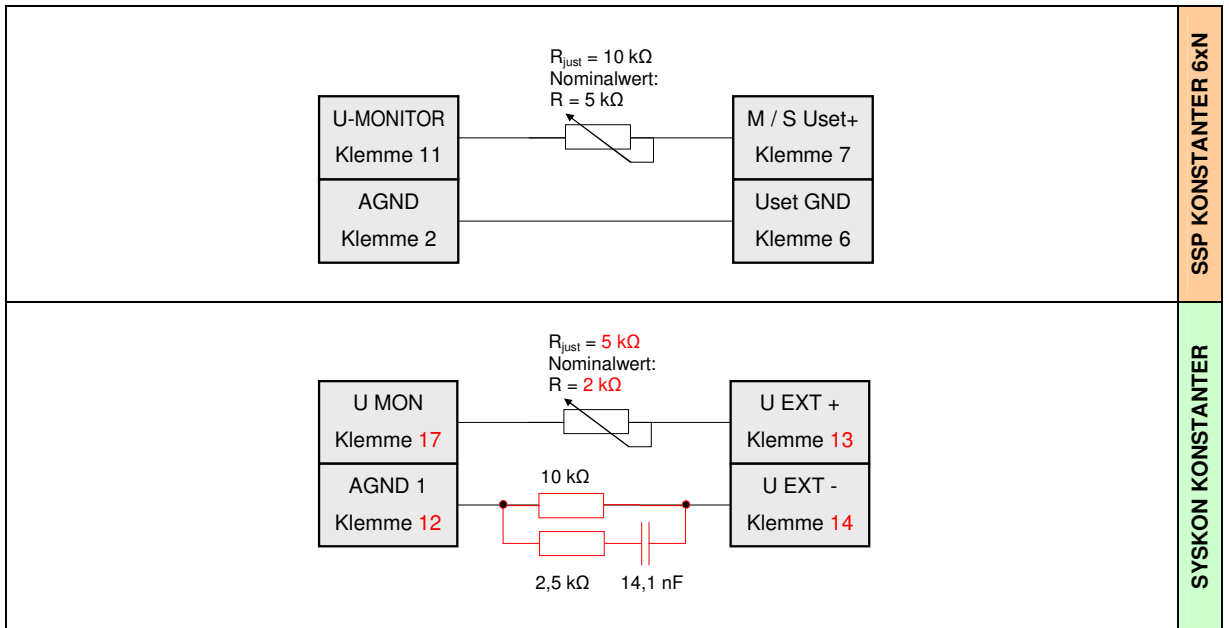
<p>Conversion table for analog current monitoring: $I_{meas_PC} = f_{I-MONITOR} \times U_{I-MONITOR}$</p> <table border="1"> <thead> <tr> <th>I_{anom}</th> <th>$f_{I-MONITOR}$</th> </tr> </thead> <tbody> <tr> <td>12.5 A</td> <td>$1.25 \frac{A}{V}$</td> </tr> <tr> <td>25 A</td> <td>$2.5 \frac{A}{V}$</td> </tr> <tr> <td>50 A</td> <td>$5 \frac{A}{V}$</td> </tr> <tr> <td>75 A</td> <td>$7.5 \frac{A}{V}$</td> </tr> <tr> <td>100 A</td> <td>$10 \frac{A}{V}$</td> </tr> <tr> <td>150 A</td> <td>$15 \frac{A}{V}$</td> </tr> </tbody> </table>	I_{anom}	$f_{I-MONITOR}$	12.5 A	$1.25 \frac{A}{V}$	25 A	$2.5 \frac{A}{V}$	50 A	$5 \frac{A}{V}$	75 A	$7.5 \frac{A}{V}$	100 A	$10 \frac{A}{V}$	150 A	$15 \frac{A}{V}$		<p>SSP KONSTANTER 6xN</p>							
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<p>Conversion table for analog current monitoring where nominal current of the SYSKON KONSTANTER is greater than that of the SSP KONSTANTER:</p> <p>$I_{meas_PC} = f_{I MON} \times U_{I MON}$ $f_{I MON} = f_{I-MONITOR(SSP)} \times f_{correction}$</p> <table border="1"> <thead> <tr> <th>SSP</th> <th>I_{anom} SYSKON</th> <th>$f_{I MON}$</th> </tr> </thead> <tbody> <tr> <td>12.5 A</td> <td>60 A</td> <td>$1.25 \frac{A}{V} \times \frac{24}{5} = 6 \frac{A}{V}$</td> </tr> <tr> <td>25 A</td> <td>60 A</td> <td>$2.5 \frac{A}{V} \times \frac{12}{5} = 6 \frac{A}{V}$</td> </tr> <tr> <td>50 A</td> <td>60 A</td> <td>$5 \frac{A}{V} \times \frac{6}{5} = 6 \frac{A}{V}$</td> </tr> <tr> <td>75 A</td> <td>120 A</td> <td>$7.5 \frac{A}{V} \times \frac{8}{5} = 12 \frac{A}{V}$</td> </tr> <tr> <td>100 A</td> <td>120 A</td> <td>$10 \frac{A}{V} \times \frac{6}{5} = 12 \frac{A}{V}$</td> </tr> <tr> <td>150 A</td> <td>180 A</td> <td>$15 \frac{A}{V} \times \frac{6}{5} = 18 \frac{A}{V}$</td> </tr> </tbody> </table>	SSP	I_{anom} SYSKON	$f_{I MON}$	12.5 A	60 A	$1.25 \frac{A}{V} \times \frac{24}{5} = 6 \frac{A}{V}$	25 A	60 A	$2.5 \frac{A}{V} \times \frac{12}{5} = 6 \frac{A}{V}$	50 A	60 A	$5 \frac{A}{V} \times \frac{6}{5} = 6 \frac{A}{V}$	75 A	120 A	$7.5 \frac{A}{V} \times \frac{8}{5} = 12 \frac{A}{V}$	100 A	120 A	$10 \frac{A}{V} \times \frac{6}{5} = 12 \frac{A}{V}$	150 A	180 A	$15 \frac{A}{V} \times \frac{6}{5} = 18 \frac{A}{V}$		<p>SYSKON KONSTANTER</p>
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Original	Replacement	Voltage $U_{I\ MON}$	Required Action Correction Factor / Terminating Resistor
SSP 500-80(-12.5)	SYSKON 1500-60-60	$U_{I\ MON}(SYSKON) = \frac{5}{24} \times U_{I-MONITOR}(SSP)$	Conversion with a factor of $\frac{24}{5}$
SSP 500-40(-25) SSP 500-52(-25) SSP 1000-80(-25)	SYSKON 1500-60-60	$U_{I\ MON}(SYSKON) = \frac{5}{12} \times U_{I-MONITOR}(SSP)$	Conversion with a factor of $\frac{12}{5}$
SSP 1000-40(-50) SSP 1000-52(-50) SSP 2000-80(-50)	SYSKON 1500-60-60	$U_{I\ MON}(SYSKON) = \frac{5}{6} \times U_{I-MONITOR}(SSP)$	Conversion with a factor of $\frac{6}{5}$
SSP 2000-80(-50)	SYSKON 3000-60-120	$U_{I\ MON}(SYSKON) = \frac{5}{12} \times U_{I-MONITOR}(SSP)$	Conversion with a factor of $\frac{12}{5}$
SSP 3000-80(-75)	SYSKON 1500-60-60	$U_{I\ MON}(SYSKON) = \frac{5}{4} \times U_{I-MONITOR}(SSP)$	32 kΩ terminating resistor
	SYSKON 3000-60-120	$U_{I\ MON}(SYSKON) = \frac{5}{8} \times U_{I-MONITOR}(SSP)$	Conversion with a factor of $\frac{8}{5}$
SSP 2000-40(-100)	SYSKON 1500-60-60	$U_{I\ MON}(SYSKON) = \frac{5}{3} \times U_{I-MONITOR}(SSP)$	12 kΩ terminating resistor
SSP 2000-52(-100)	SYSKON 3000-60-120	$U_{I\ MON}(SYSKON) = \frac{5}{6} \times U_{I-MONITOR}(SSP)$	Conversion with a factor of $\frac{6}{5}$
SSP 3000-40(-150)	SYSKON 3000-60-120	$U_{I\ MON}(SYSKON) = \frac{5}{4} \times U_{I-MONITOR}(SSP)$	32 kΩ terminating resistor
SSP 3000-52(-150)	SYSKON 4500-60-180	$U_{I\ MON}(SYSKON) = \frac{5}{6} \times U_{I-MONITOR}(SSP)$	Conversion with a factor of $\frac{6}{5}$

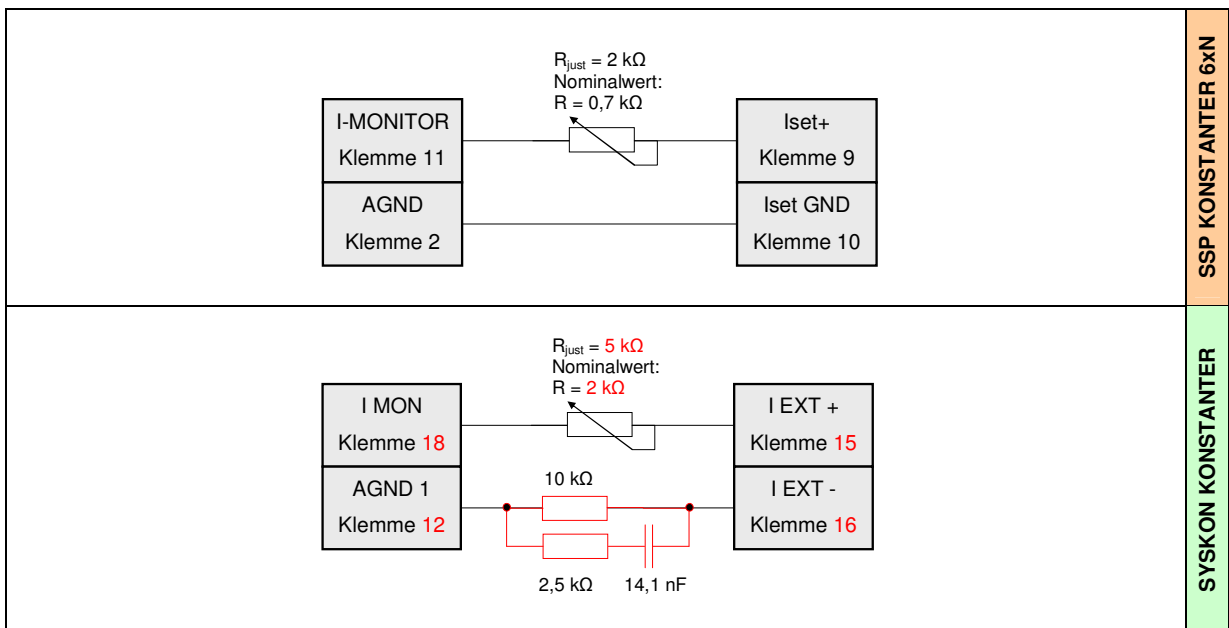
1.8. External Voltage Sensor



1.9. Voltage Regulation with Series Master-Slave Connection



1.10. Current Regulation with Parallel Master-Slave Connection



2. Technical Characteristics of the Analog Interface, Sorted by Function

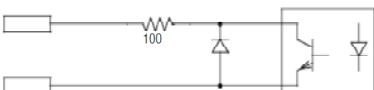
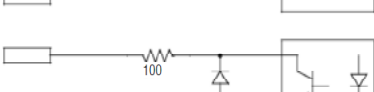
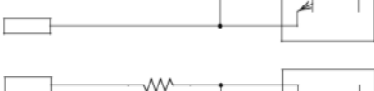
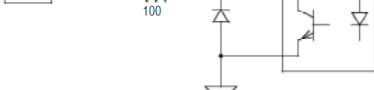

2.1. Auxiliary Power

<p>Open circuit voltage: 15 V ± 3% Internal resistance: 510 Ω + 25 Ω (PTC) Voltage under load: 10 mA 9.7 V 25 mA 1.6 V 50 mA --- 60 mA ---</p>	<p>Klemme 1 Klemme 2</p>	SSP KONSTANTER 6xN
<p>Open circuit voltage: 18.5 V Internal resistance: 20 Ω + 25 Ω (PTC) Voltage under load: 10 mA 18.0 V 25 mA 17.4 V 50 mA 16.3 V 60 mA 15.8 V 63 mA → 0 V</p>	<p>+15V / Klemme 11 AGND 1 / Klemme 12 AGND 2 / Klemme 10</p>	SYSKON KONSTANTER

2.2. Trigger Input

<p>Operating voltage: Low: 0 V ≤ U_s ≤ 1 V High: 4 V ≤ U_s ≤ 26 V Internal resistance: 1.5 kΩ</p>	<p>Klemme 3 Klemme 4</p>	SSP KONSTANTER 6xN
<p>Operating voltage: Low: -18 V ≤ U_s ≤ 1 V High: 4 V ≤ U_s ≤ 18 V Internal resistance: 1.47 kΩ</p>	<p>TRG 1 + / Klemme 1 TRG 1 - / Klemme 2 TRG 2 + / Klemme 3 TRG 2 - / Klemme 4</p>	SYSKON KONSTANTER

2.3. Signal output

None		SSP KONSTANTER 6xN
<p>Operating voltage: Max. 30 V Operating current: Max. 20 mA Internal resistance: 100 Ω</p>	<p>SIG 1 + / Klemme 5 </p> <p>SIG 1 - / Klemme 6 </p> <p>SIG 2 + / Klemme 7 </p> <p>SIG 2 - / Klemme 8 </p> <p>SIG 3 + / Klemme 9 </p>	SYSKON KONSTANTER

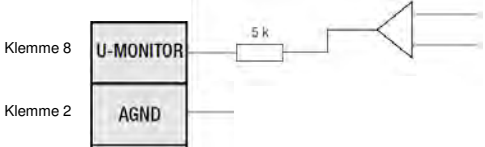
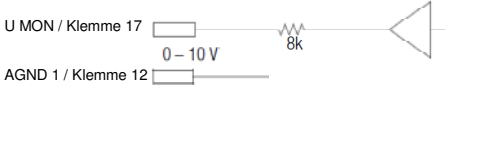
2.4. Regulating Output Voltage

<p>Differential voltage input The output voltage setpoint is the sum of the analog setpoint and the digitally selected setpoint. $U_{setsum} = USET + U_{setanalog}$ $U_{setanalog} = k_{uset} \times U_{cu}$</p> <p>Control voltage U_{cu}: $-5 V \leq U_{cu} \leq +5 V$ $-U_{nom} \leq U_{setanalog} \leq + U_{nom}$</p> <table border="0"> <tr> <td>U_{nom}</td> <td>40 V</td> <td>52 V</td> <td>80 V</td> <td>Nominal output voltage</td> </tr> <tr> <td>k_{uset}</td> <td>8</td> <td>10.4</td> <td>16</td> <td>Gain, control coefficient</td> </tr> <tr> <td>U_{cu}</td> <td colspan="3"></td> <td>$U_{terminal 5} - U_{terminal 6}$</td> </tr> <tr> <td>$U_{setanalog}$</td> <td colspan="3"></td> <td>Analog controlled output voltage setpoint</td> </tr> <tr> <td>USET</td> <td colspan="3"></td> <td>Digitally controlled output voltage setpoint</td> </tr> <tr> <td>$U_{setsum} \leq 1.2 \times U_{nom}$</td> <td colspan="3"></td> <td>Output voltage setpoint, combined analog and digital</td> </tr> </table> <p>Internal resistance: Uset+ 10 kΩ Uset GND 16.56 kΩ</p>	U_{nom}	40 V	52 V	80 V	Nominal output voltage	k_{uset}	8	10.4	16	Gain, control coefficient	U_{cu}				$U_{terminal 5} - U_{terminal 6}$	$U_{setanalog}$				Analog controlled output voltage setpoint	USET				Digitally controlled output voltage setpoint	$U_{setsum} \leq 1.2 \times U_{nom}$				Output voltage setpoint, combined analog and digital		<p>SSP KONSTANTER 6xN</p>
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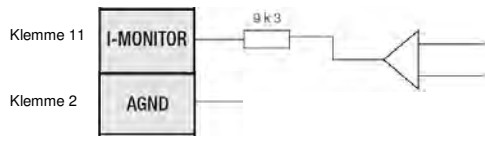
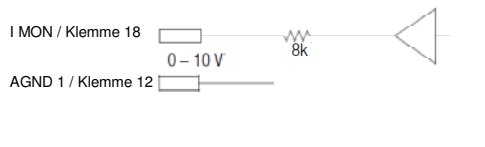
2.5. Regulating Output Current

<p>Differential voltage input The output current setpoint is the sum of the analog setpoint and the digitally selected setpoint. $I_{setsum} = ISET + I_{setanalog}$ $I_{setanalog} = k_{iset} \times U_{ci}$</p> <p>Control voltage U_{ci}: $-5 V \leq U_{ci} \leq +5 V$ $-I_{nom} \leq I_{setanalog} \leq + I_{nom}$</p> <table border="0"> <tr> <td>I_{nom}</td> <td>12.5 A</td> <td>25 A</td> <td>50 A</td> <td>75 A</td> <td>100 A</td> <td>150 A</td> <td>Nominal output current</td> </tr> <tr> <td>k_{iset}</td> <td>2.5 A/V</td> <td>5 A/V</td> <td>10 A/V</td> <td>15 A/V</td> <td>20 A/V</td> <td>30 A/V</td> <td>Gain, control coefficient</td> </tr> <tr> <td>U_{ci}</td> <td colspan="6"></td> <td>$U_{terminal 5} - U_{terminal 6}$</td> </tr> <tr> <td>$U_{setanalog}$</td> <td colspan="6"></td> <td>Analog controlled output current setpoint</td> </tr> <tr> <td>ISET</td> <td colspan="6"></td> <td>Digitally controlled output current setpoint</td> </tr> <tr> <td>$I_{setsum} \leq 1.2 \times U_{nom}$</td> <td colspan="6"></td> <td>Output current setpoint, combined analog and digital</td> </tr> </table> <p>Internal resistance: Iset+ 10 kΩ Iset GND 16.56 kΩ</p>	I_{nom}	12.5 A	25 A	50 A	75 A	100 A	150 A	Nominal output current	k_{iset}	2.5 A/V	5 A/V	10 A/V	15 A/V	20 A/V	30 A/V	Gain, control coefficient	U_{ci}							$U_{terminal 5} - U_{terminal 6}$	$U_{setanalog}$							Analog controlled output current setpoint	ISET							Digitally controlled output current setpoint	$I_{setsum} \leq 1.2 \times U_{nom}$							Output current setpoint, combined analog and digital		<p>SSP KONSTANTER 6xN</p>
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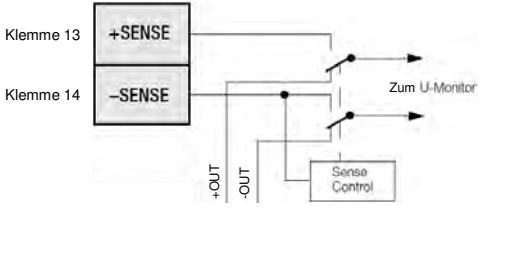
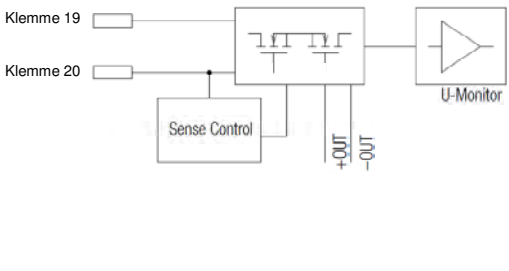
2.6. Analog Measured Value for Output Voltage

<p>Output voltage measured to AGND: $U_{U-MONITOR} = k_{U_{actual}} \times U_{actual}$</p> <p>Measured value range $U_{U-MONITOR}$: $0 V \leq U_{U-MONITOR} \leq 10 V$ Output voltage U_{actual}: $0 V \leq U_{actual} \leq + U_{nom}$</p> <table border="0"> <tr> <td>U_{nom}</td> <td>40 V</td> <td>52 V</td> <td>80 V</td> <td rowspan="2">Nominal output voltage Gain, measuring coefficient</td> </tr> <tr> <td>$k_{U_{actual}}$</td> <td>$\frac{1}{4}$</td> <td>$\frac{1}{5,2}$</td> <td>$\frac{1}{8}$</td> </tr> </table> <p>$U_{U-MONITOR}$ $U_{terminal 8} - U_{terminal 2}$</p> <p>Internal resistance: 5 kΩ</p>	U_{nom}	40 V	52 V	80 V	Nominal output voltage Gain, measuring coefficient	$k_{U_{actual}}$	$\frac{1}{4}$	$\frac{1}{5,2}$	$\frac{1}{8}$		SSP KONSTANTER 6xN
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U_{nom}	60 V	Nominal output voltage Gain, measuring coefficient									
$k_{U_{actual}}$	$\frac{1}{6}$										

2.7. Analog Measured Value for Output Current

<p>Output current measured to AGND: $U_{I-MONITOR} = k_{I_{actual}} \times I_{actual}$</p> <p>Measured value range $U_{I-MONITOR}$: $0 V \leq U_{I-MONITOR} \leq 10 V$ Output current I_{actual}: $0 A \leq I_{actual} \leq + I_{nom}$</p> <table border="0"> <tr> <td>I_{nom}</td> <td>12,5 A</td> <td>25 A</td> <td>50 A</td> <td>75 A</td> <td>100 A</td> <td>150 A</td> <td rowspan="2">Nominal output current Gain, measuring coefficient</td> </tr> <tr> <td>$k_{I_{actual}}$</td> <td>$\frac{4}{5} \frac{V}{A}$</td> <td>$\frac{2}{5} \frac{V}{A}$</td> <td>$\frac{1}{5} \frac{V}{A}$</td> <td>$\frac{2}{15} \frac{V}{A}$</td> <td>$\frac{1}{10} \frac{V}{A}$</td> <td>$\frac{1}{15} \frac{V}{A}$</td> </tr> </table> <p>$U_{I-MONITOR}$ $U_{terminal 11} - U_{terminal 2}$</p> <p>Internal resistance: 9.3 kΩ</p>	I_{nom}	12,5 A	25 A	50 A	75 A	100 A	150 A	Nominal output current Gain, measuring coefficient	$k_{I_{actual}}$	$\frac{4}{5} \frac{V}{A}$	$\frac{2}{5} \frac{V}{A}$	$\frac{1}{5} \frac{V}{A}$	$\frac{2}{15} \frac{V}{A}$	$\frac{1}{10} \frac{V}{A}$	$\frac{1}{15} \frac{V}{A}$		SSP KONSTANTER 6xN
I_{nom}	12,5 A	25 A	50 A	75 A	100 A	150 A	Nominal output current Gain, measuring coefficient										
$k_{I_{actual}}$	$\frac{4}{5} \frac{V}{A}$	$\frac{2}{5} \frac{V}{A}$	$\frac{1}{5} \frac{V}{A}$	$\frac{2}{15} \frac{V}{A}$	$\frac{1}{10} \frac{V}{A}$	$\frac{1}{15} \frac{V}{A}$											
<p>Output current measured to AGND: $U_{I-MONITOR} = k_{I_{actual}} \times I_{actual}$</p> <p>Measured value range $U_{I-MONITOR}$: $0 V \leq U_{I-MONITOR} \leq 10 V$ Output current I_{actual}: $0 A \leq I_{actual} \leq + I_{nom}$</p> <table border="0"> <tr> <td>I_{nom}</td> <td>60 A</td> <td>120 A</td> <td>180 A</td> <td rowspan="2">Nominal output current Gain, measuring coefficient</td> </tr> <tr> <td>$k_{I_{actual}}$</td> <td>$\frac{1}{6} \frac{V}{A}$</td> <td>$\frac{1}{12} \frac{V}{A}$</td> <td>$\frac{1}{18} \frac{V}{A}$</td> </tr> </table> <p>$U_{I-MONITOR}$ $U_{terminal 18} - U_{terminal 12}$</p> <p>Internal resistance: 8 kΩ</p>	I_{nom}	60 A	120 A	180 A	Nominal output current Gain, measuring coefficient	$k_{I_{actual}}$	$\frac{1}{6} \frac{V}{A}$	$\frac{1}{12} \frac{V}{A}$	$\frac{1}{18} \frac{V}{A}$		SYSKON KONSTANTER						
I_{nom}	60 A	120 A	180 A	Nominal output current Gain, measuring coefficient													
$k_{I_{actual}}$	$\frac{1}{6} \frac{V}{A}$	$\frac{1}{12} \frac{V}{A}$	$\frac{1}{18} \frac{V}{A}$														

2.8. External Voltage Sensor

<p>Switching to 4-wire operation takes place automatically when the –SENSE lead is connected to the appropriate output pole or negative load pole.</p>		<p>SSP KONSTANTER 6xN</p>
<p>Switching to 4-wire operation takes place automatically when the –SENSE lead is connected to the appropriate output pole or negative load pole.</p>		<p>SYSKON KONSTANTER</p>

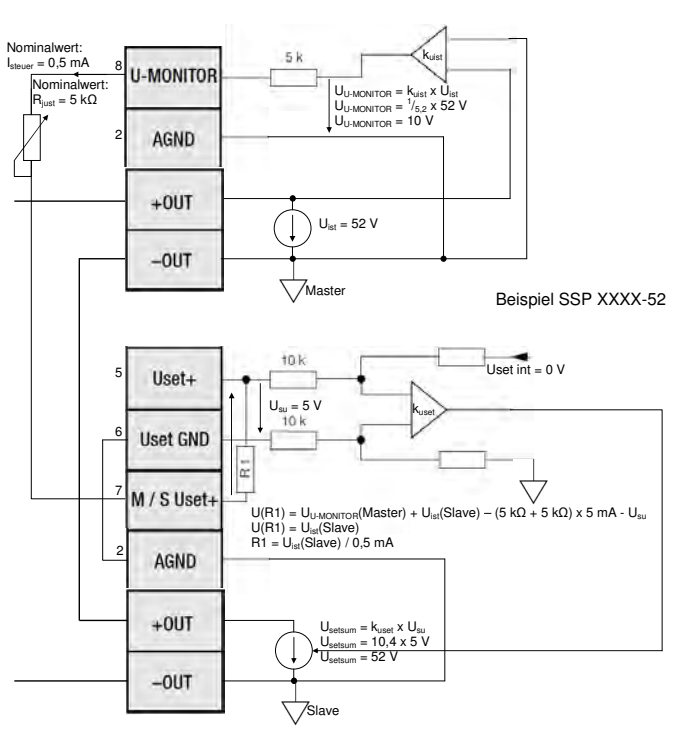
2.9. Voltage Regulation with Series Master-Slave Connection

As a result of high impedance resistor R1 at the M/S-Uset+ input, a current of 0.5 mA occurs at nominal output voltage.

In order to assure that this is the case, the below specified R1 resistance values are integrated into instruments with various nominal voltages.

U_{nom}	40 V	52 V	80 V
R1	80 kΩ	104 kΩ	160 kΩ

A 10 kΩ ten-turn potentiometer can be used as a trimming resistor.
However, one 4.5 kΩ and one 1 kΩ ten-turn potentiometer, connected in series, can be used for finer adjustability.

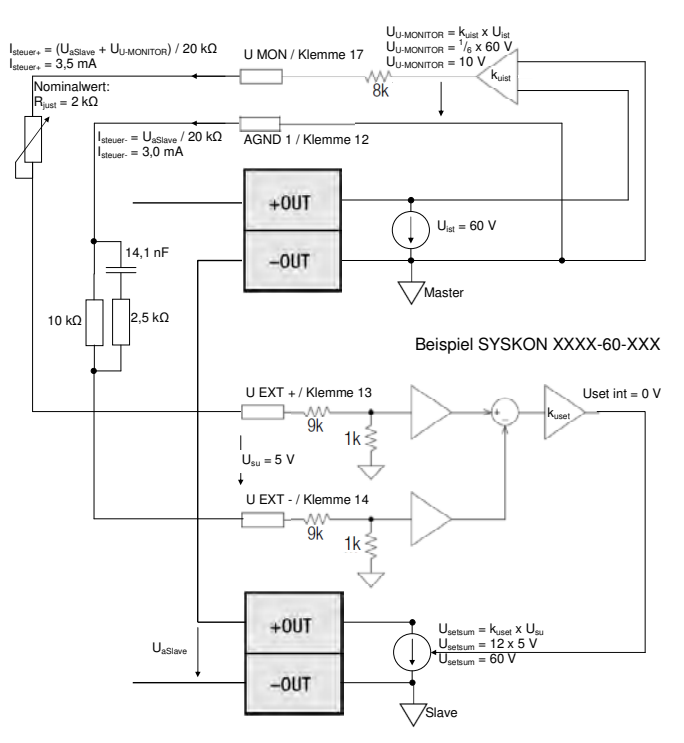


SSP KONSTANTER 6xN

A 5 kΩ ten-turn potentiometer can be used as a trimming resistor.
However, one 1.75 kΩ and one 500 Ω ten-turn potentiometer, connected in series, can be used for finer adjustability.

Due to the layout of the differential amplifier input for voltages of up to 120 V to internal AGND, no high impedance series resistor is required in addition to the trimming resistor.

The network in the inverse feedback path is used for stabilization.

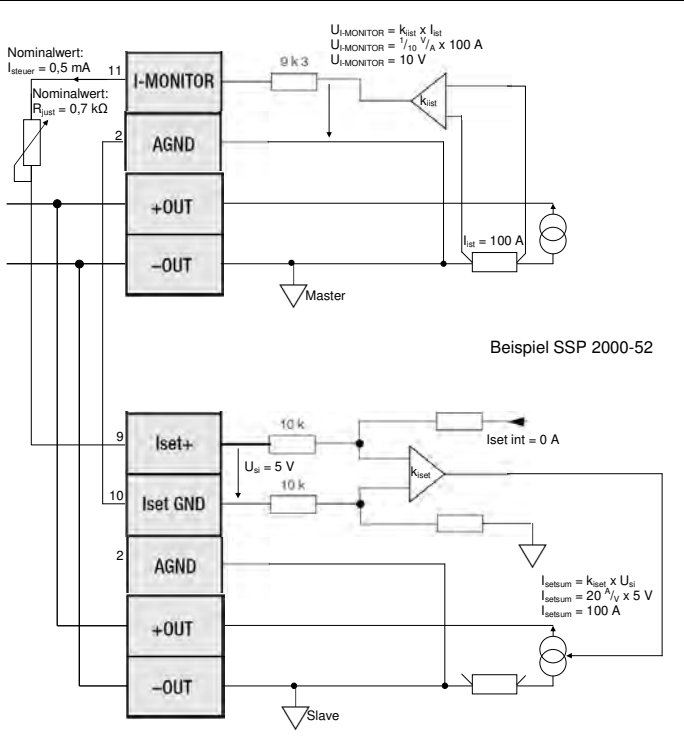


SYSKON KONSTANTER

2.10. Current Regulation with Parallel Master-Slave Connection

A 2 kΩ ten-turn potentiometer can be used as a trimming resistor.

The slave's differential input is not 100% compensated (see internal resistor at the current regulating input).

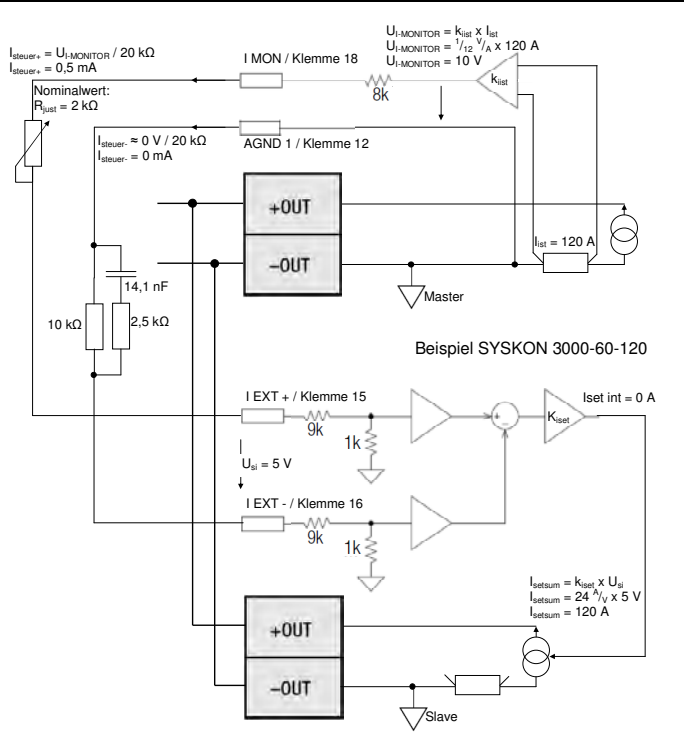


SSP KONSTANTER 6xN

A 5 kΩ ten-turn potentiometer can be used as a trimming resistor.

However, one 1.75 kΩ and one 500 Ω ten-turn potentiometer, connected in series, can be used for finer adjustability.

The network in the inverse feedback path is used for stabilization.



SYSKON KONSTANTER

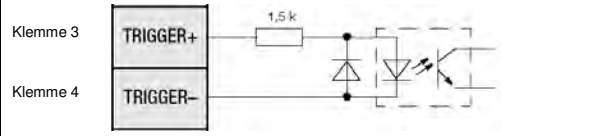
3. Technical Characteristics of the Analog Interface, Sorted by Instrument Type

3.1. SSP KONSTANTER

3.1.1. Auxiliary Power

Open circuit voltage:	15 V ± 3%	
Internal resistance:	510 Ω + 25 Ω (PTC)	
Voltage under load:	10 mA 9.7 V	
	25 mA 1.6 V	
	50 mA ---	
	60 mA ---	

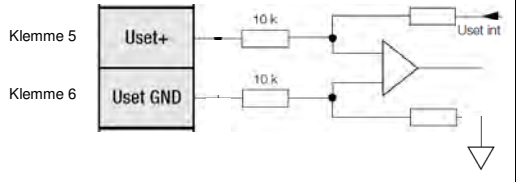
3.1.2. Trigger Input

Operating voltage:	Low: 0 V ≤ U _s ≤ 1 V High: 4 V ≤ U _s ≤ 26 V	
Internal resistance:	1.5 kΩ	

3.1.3. Signal output

None

3.1.4. Regulating Output Voltage

<p>Differential voltage input The output voltage setpoint is the sum of the analog setpoint and the digitally selected setpoint.</p> $U_{setsum} = USET + U_{setanalog}$ $U_{setanalog} = k_{uset} \times U_{cu}$		
Control voltage U _{cu} :		-5 V ≤ U _{cu} ≤ +5 V -U _{nom} ≤ U _{setanalog} ≤ +U _{nom}
U _{nom}		40 V 52 V 80 V Nominal output voltage
k _{uset}		8 10.4 16 Gain, control coefficient
U _{cu}		U _{terminal 5} - U _{terminal 6}
U _{setanalog}		Analog controlled output voltage setpoint
USET		Digitally controlled output voltage setpoint
U _{setsum} ≤ 1.2 × U _{nom}		Output voltage setpoint, combined analog and digital
Internal resistance:		Uset+ 10 kΩ Uset GND 16.56 kΩ Ω

3.1.5. Regulating Output Current

<p>Differential voltage input The output current setpoint is the sum of the analog setpoint and the digitally selected setpoint. $I_{setsum} = ISET + I_{setanalog}$ $I_{setanalog} = k_{iset} \times U_{ci}$</p>		
<p>Control voltage U_{ci}: $-5 V \leq U_{ci} \leq +5 V$ $-I_{nom} \leq I_{setanalog} \leq +I_{nom}$</p>		
<p>I_{nom} 12.5 A 25 A 50 A 75 A 100 A 150 A</p>	<p>Nominal output current</p>	
<p>k_{iset} 2.5 $\frac{A}{V}$ 5 $\frac{A}{V}$ 10 $\frac{A}{V}$ 15 $\frac{A}{V}$ 20 $\frac{A}{V}$ 30 $\frac{A}{V}$</p>	<p>Gain, control coefficient</p>	
<p>U_{ci} $U_{setanalog}$</p>	<p>$U_{terminal 5} - U_{terminal 6}$ Analog controlled output current setpoint</p>	
<p>ISET</p>	<p>Digitally controlled output current setpoint</p>	
<p>$I_{setsum} \leq 1.2 \times U_{nom}$</p>	<p>Output current setpoint, combined analog and digital</p>	
<p>Internal resistance:</p>	<p>Iset+ 10 kΩ Iset GND 16.56 kΩ</p>	

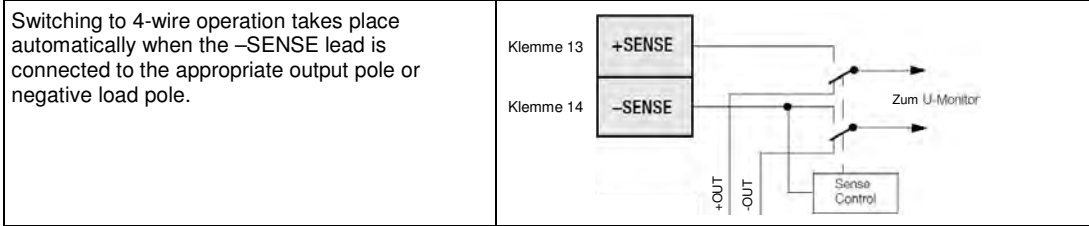
3.1.6. Analog Measured Value for Output Voltage

<p>Output voltage measured to AGND: $U_{U-MONITOR} = k_{uactual} \times U_{actual}$</p>		
<p>Measured value range $U_{U-MONITOR}$: $0 V \leq U_{U-MONITOR} \leq 10 V$ Output voltage U_{actual}: $0 V \leq U_{actual} \leq +U_{nom}$</p>		
<p>U_{nom} 40 V 52 V 80 V</p>	<p>Nominal output voltage</p>	
<p>$k_{uactual}$ 1/4 1/5,2 1/8</p>	<p>Gain, measuring coefficient</p>	
<p>$U_{U-MONITOR}$</p>	<p>$U_{terminal 8} - U_{terminal 2}$</p>	
<p>Internal resistance:</p>	<p>5 kΩ</p>	

3.1.7. Analog Measured Value for Output Current

<p>Output current measured to AGND: $U_{I-MONITOR} = k_{iactual} \times I_{actual}$</p>		
<p>Measured value range $U_{I-MONITOR}$: $0 V \leq U_{I-MONITOR} \leq 10 V$ Output current I_{actual}: $0 A \leq I_{actual} \leq +I_{nom}$</p>		
<p>I_{nom} 12.5 A 25 A 50 A 75 A 100 A 150 A</p>	<p>Nominal output current</p>	
<p>$k_{iactual}$ 4/5 $\frac{V}{A}$ 2/5 $\frac{V}{A}$ 1/5 $\frac{V}{A}$ 2/15 $\frac{V}{A}$ 1/10 $\frac{V}{A}$ 1/15 $\frac{V}{A}$</p>	<p>Gain, measuring coefficient</p>	
<p>$U_{I-MONITOR}$</p>	<p>$U_{terminal 11} - U_{terminal 2}$</p>	
<p>Internal resistance:</p>	<p>9.3 kΩ</p>	

3.1.8. External Voltage Sensor



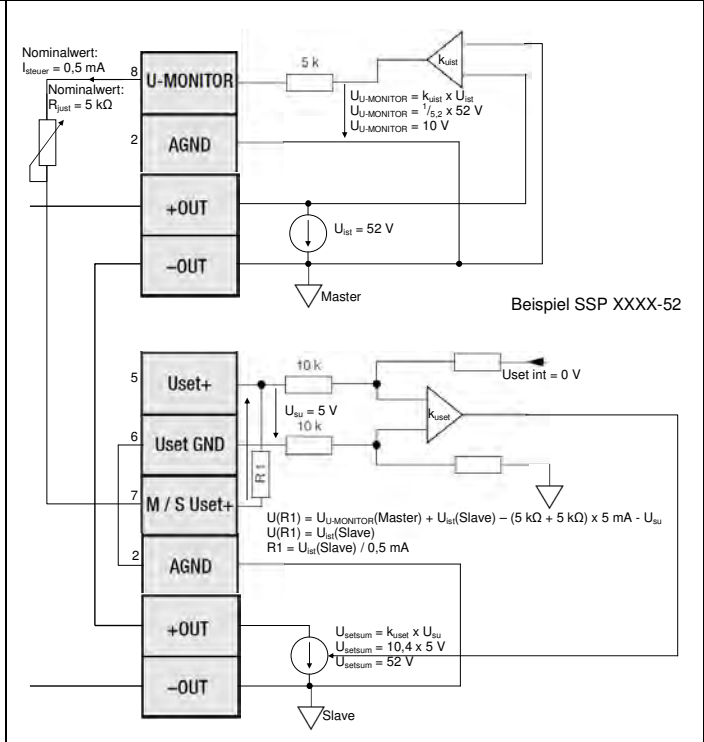
3.1.9. Voltage Regulation with Series Master-Slave Connection

As a result of high impedance resistor R1 at the M/S-Uset+ input, a current of 0.5 mA occurs at nominal output voltage.

In order to assure that this is the case, the below specified R1 resistance values are integrated into instruments with various nominal voltages.

U_{nom}	40 V	52 V	80 V
R1	80 kΩ	104 kΩ	160 kΩ

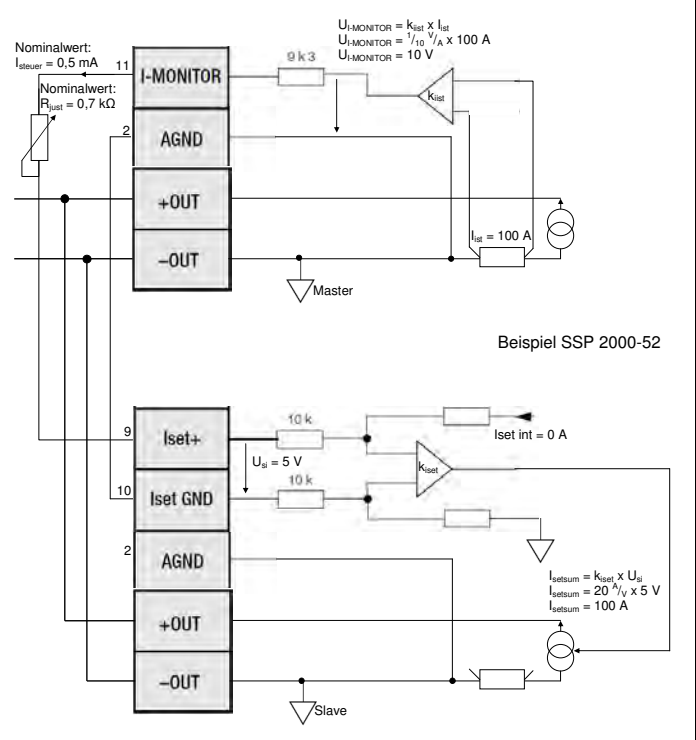
A 10 kΩ ten-turn potentiometer can be used as a trimming resistor. However, one 4.5 kΩ and one 1 kΩ ten-turn potentiometer, connected in series, can be used for finer adjustability.



3.1.10. Current Regulation with Parallel Master-Slave Connection

A 2 kΩ ten-turn potentiometer can be used as a trimming resistor.

The slave's differential input is not 100% compensated. (see internal resistor at the current regulating input)



3.2. SYSKON KONSTANTER

3.2.1. Auxiliary Power

Open circuit voltage:	18.5 V	
Internal resistance:	20 Ω + 25 Ω (PTC)	
Voltage under load:	10 mA 18.0 V	
	25 mA 17.4 V	
	50 mA 16.3 V	
	60 mA 15.8 V	
	63 mA → 0 V	

3.2.2. Trigger Input

Operating voltage:	Low: $-18\text{ V} \leq U_s \leq 1\text{ V}$ High: $4\text{ V} \leq U_s \leq 18\text{ V}$	
Internal resistance:	1.47 kΩ	

3.2.3. Signal output

Operating voltage:	Max. 30 V	
Operating current:	Max. 20 mA	
Internal resistance:	100 Ω	

3.2.4. Regulating Output Voltage

<p>Differential voltage input The output voltage setpoint is the sum of the analog setpoint and the digitally selected setpoint.</p> $U_{\text{setsum}} = U_{\text{SET}} + U_{\text{setanalog}}$ $U_{\text{setanalog}} = k_{\text{uset}} \times U_{\text{cu}}$		
Control voltage U_{cu} :	$-5\text{ V} \leq U_{\text{cu}} \leq +5\text{ V}$ $-U_{\text{nom}} \leq U_{\text{setanalog}} \leq +U_{\text{nom}}$	
U_{nom}	60 V	<p>Nominal output voltage Gain, control coefficient $U_{\text{terminal 13}} - U_{\text{terminal 14}}$ Analog controlled output voltage setpoint Digitally controlled output voltage setpoint Output voltage setpoint, combined analog and digital</p>
k_{uset}	12	
U_{cu}		
$U_{\text{setanalog}}$		
USET		
	$U_{\text{setsum}} \leq 1.1 \times U_{\text{nom}}$	
Internal resistance:	U EXT + 10 kΩ U EXT - 10 kΩ	

3.2.5. Regulating Output Current

<p>Differential voltage input The output current setpoint is the sum of the analog setpoint and the digitally selected setpoint.</p> $I_{setsum} = ISET + I_{setanalog}$ $I_{setanalog} = k_{iset} \times U_{ci}$		
<p>Control voltage U_{ci}: $-5 V \leq U_{ci} \leq +5 V$ $-I_{nom} \leq I_{setanalog} \leq +I_{nom}$</p>		
I_{nom}	60 A 120 A 180 A	<p>Nominal output current Gain, control coefficient</p>
k_{iset}	$12 \frac{A}{V}$ $24 \frac{A}{V}$ $36 \frac{A}{V}$	
U_{ci}		<p>$U_{terminal 15} - U_{terminal 16}$ Analog controlled output current setpoint</p>
$U_{setanalog}$		
ISET		Digitally controlled output current setpoint
$I_{setsum} \leq 1.2 \times U_{nom}$		Output current setpoint, combined analog and digital
Internal resistance:		I EXT + 10 kΩ I EXT - 10 kΩ

3.2.6. Analog Measured Value for Output Voltage

Output voltage measured to AGND:	$U_{U-MONITOR} = k_{uactual} \times U_{actual}$	
Measured value range	$0 V \leq U_{U-MONITOR} \leq 10 V$	
$U_{U-MONITOR}$:	$0 V \leq U_{actual} \leq +U_{nom}$	<p>Nominal output voltage Gain, measuring coefficient</p>
Output voltage U_{actual} :		
U_{nom}	60 V	<p>$U_{terminal 17} - U_{terminal 12}$</p>
$k_{uactual}$	$\frac{1}{6}$	
$U_{U-MONITOR}$		
Internal resistance:		8 kΩ

3.2.7. Analog Measured Value for Output Current

Output current measured to AGND:	$U_{I-MONITOR} = k_{iactual} \times I_{actual}$	
Measured value range	$0 V \leq U_{I-MONITOR} \leq 10 V$	
$U_{I-MONITOR}$:	$0 A \leq I_{actual} \leq +I_{nom}$	<p>Nominal output current Gain, measuring coefficient</p>
Output current I_{actual} :		
I_{nom}	60 A 120 A 180 A	<p>$U_{terminal 18} - U_{terminal 12}$</p>
$k_{iactual}$	$\frac{1}{6} \frac{V}{A}$ $\frac{1}{12} \frac{V}{A}$ $\frac{1}{18} \frac{V}{A}$	
$U_{I-MONITOR}$		
Internal resistance:		8 kΩ

3.2.8. External Voltage Sensor

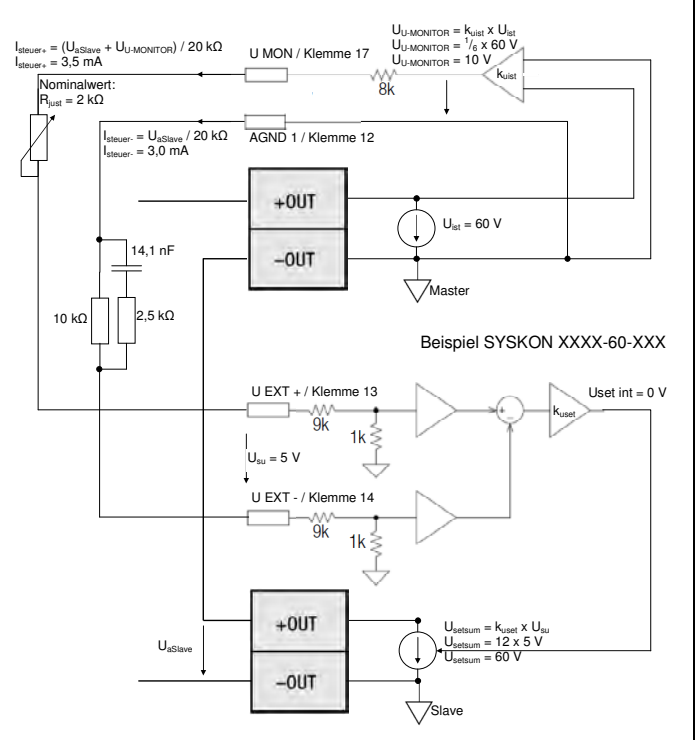
<p>Switching to 4-wire operation takes place automatically when the –SENSE lead is connected to the appropriate output pole or negative load pole.</p>	
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3.2.9. Voltage Regulation with Series Master-Slave Connection

A 5 kΩ ten-turn potentiometer can be used as a trimming resistor.
 However, one 1.75 kΩ and one 500 Ω ten-turn potentiometer, connected in series, can be used for finer adjustability.

Due to the layout of the differential amplifier input for voltages of up to 120 V to internal AGND, no high impedance series resistor is required in addition to the trimming resistor.

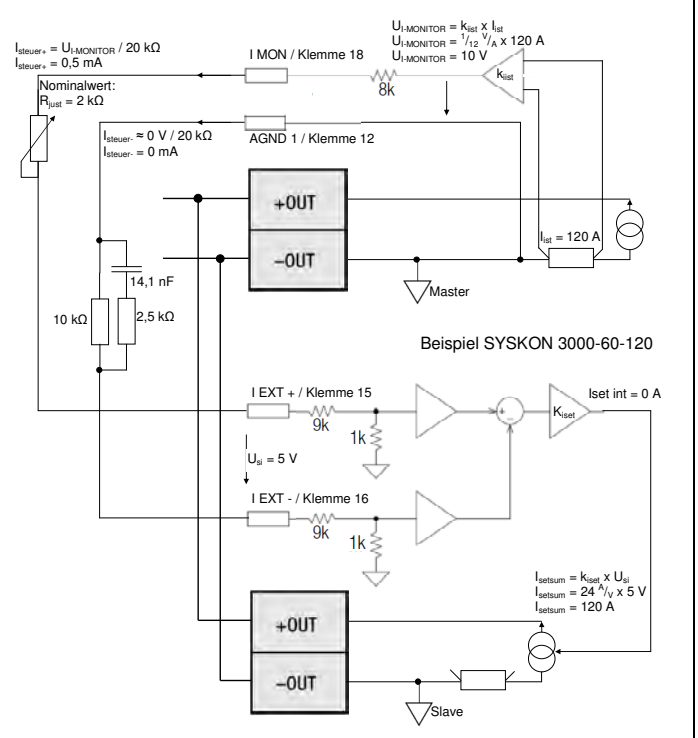
The network in the inverse feedback path is used for stabilization.



3.2.10. Current Regulation with Parallel Master-Slave Connection

A 5 kΩ ten-turn potentiometer can be used as a trimming resistor.
 However, one 1.75 kΩ and one 500 Ω ten-turn potentiometer, connected in series, can be used for finer adjustability.

The network in the inverse feedback path is used for stabilization.



Developed in Germany • subject to alterations



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